Inverse transformation method

1 Non uniform random numbers

We illiustrate with Python the method of the Inverse Transformation method (and as usual the efficiency of the Python code by using the module time) .

1. Write a Python code which stores in an array 1000000 random numbers by using two methods : the member function exponential of the module np.random and the member function uniform (with a scale equal to 1) and using the inverse transformation uniform. Compare the elasped times of the two methods and display the histograms associated with the two methods on the same graph.
2. We want to illustrate with Python the method of the Box Müller method (and as usual the efficiency of the Python code by using the module time). Write a Python code which stores in an array 1000000 random numbers by using two methods : the member function randn of the module np.random and the member function uniform (with a scale equal to 1) and using the inverse transformation uniform. Compare the elapsed times of the two methods and display the histograms associated with the two methods on the same graph. By using some trickn obtain a ratio of the elapsed times less than 1.5
3. Generate 100 two-dimensional unit vectors uniformly. Plot the vectors by using the function **quiver** of **matplotlib.pyplot**.
4. By using 10000 independent runs, compute the average of each run (along 0x and 0y) and store results in two arrays. Build and plot the two histograms. Show that the distributions are well fitted by Gaussian distribution with a variance 1/2.
5. Generate 100 three-dimensional unit vectors uniformly. Plot the vectors by using the function **quiver** of **matplotlib.pyplot**.
6. By using 10000 independent runs, compute the average of each run (along 0x and 0y) and store results in three arrays. Build and plot the two histograms. Show that the distributions are well fitted by Gaussian distribution with a variance 1/3.