

Quasi integrability of the sixteen-vertex model

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We analyze the symmetries of the sixteen-vertex model. We prove the existence of a natural parametrization of the parameter space of the model by elliptic curves, grounding the inversion trick for the exact calculation of the partition function. We proceed with a “pre-Bethe-ansatz” system of equations whose analysis produces an algebraic modular invariant and yields candidates for criticality and disorder conditions.

1. Introduction

The results we describe here concern statistical mechanics on lattices (vertex models for the case). We emphasize the existence of a large group of symmetry acting on the parameter space of lattice models, and analyze these symmetries in the case of the general sixteen-vertex model on a two-dimensional square lattice. Our results take their roots in the theory of integrable lattice models [1] in statistical mechanics and field theory, but concern very general (integrable or not) models, and in particular extend to higher dimensions.

One of the recurrent features of integrability is the emergence of algebraic curves in the parametrization of the models. These curves are the core of the resolution of the models, be it through the Bethe ansatz [2,3], the description of the solutions of the Yang–Baxter equations, or the implementation of inversion relations [4,5]. We have shown recently how these curves may be *generated* by the action of an infinite group (denoted Γ in the sequel), which happens to be the symmetry group of the Yang–Baxter equations, and we have correspondingly introduced the notion of quasi-integrability (see refs. [6–10]). What is essential is that the group Γ not only acts as a symmetry of integrability but *is a symmetry group of the whole phase diagram whatever the model is*. This

is what we use here in the case of the sixteen-vertex model on a square lattice [11], aiming at exact results *beyond the border of integrability*.

We show that the orbits of the group Γ stay on elliptic curves in the parameter space, furnishing the most appropriate parametrization to describe the physics of the model. We give the equations of these curves. We then show how the action of Γ is compatible with weak graph duality (gauge) symmetries [12,11] and give a full set of algebraically independent gauge invariants, with remarkable transformation properties under Γ . We proceed with a “pre-Bethe-ansatz” system of equations whose analysis produces an algebraic *modular invariant*, and candidates for criticality and disorder conditions.

2. The model

The model is a vertex model on a square lattice, with spins taking two values on each bond. The Boltzmann weights are arranged in a 4×4 matrix R of entries r_{kl}^{ij} corresponding to the configuration

$$\begin{array}{ccc} & l & \\ i & \text{---} & k \\ & j & \end{array}.$$

We alternatively use for R the notation

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$$R = \begin{pmatrix} r_{11}^{11} & r_{11}^{12} & r_{11}^{21} & r_{11}^{22} \\ r_{12}^{11} & r_{12}^{12} & r_{12}^{21} & r_{12}^{22} \\ r_{21}^{11} & r_{21}^{12} & r_{21}^{21} & r_{21}^{22} \\ r_{22}^{11} & r_{22}^{12} & r_{22}^{21} & r_{22}^{22} \end{pmatrix} = \begin{pmatrix} a_1 & a_2 & b_1 & b_2 \\ a_3 & a_4 & b_3 & b_4 \\ c_1 & c_2 & d_1 & d_2 \\ c_3 & c_4 & d_3 & d_4 \end{pmatrix}.$$

The model is insensitive to a rescaling of all entries by a common factor. The complexified parameter space is thus the projective space CP_{15} . A number of transformations act on R : the group Γ of symmetries of the Yang-Baxter equations, and the group G of gauge transformations. We shall also describe in section 5 a larger group G_{Bethes} , containing G as a subgroup.

2.1. The group Γ

It is generated by involutions represented by *non-linear* (birational) transformations [6-10]: the inversion I (inverse for the 4×4 product in \mathcal{M}), the partial transpositions t_1 and t_2 , and the full transposition t defined by

$$\sum_{\alpha\beta} (IR)_{\alpha\beta}^{ij} \cdot r_{kl}^{\alpha\beta} = \lambda \delta_k^i \delta_l^j, \tag{1}$$

with λ an arbitrary multiplicative factor, and

$$(t_1 R)_{kl}^{ij} = r_{il}^{kj}, \quad (t_2 R)_{kl}^{ij} = r_{kj}^{il}, \quad t = t_1 t_2. \tag{2}$$

The matrix R is an element in $\mathcal{M} = \mathcal{A} \otimes \mathcal{A}$ with \mathcal{A} the algebra of 2×2 matrices. The indices 1 and 2 recall that we act only on the first (respectively) second factor \mathcal{A} in \mathcal{M} . The inversion I commutes with t but does not commute with t_1 or t_2 .

2.2. The group G

In contrast, the gauge group $G = sl_2 \times sl_2$ acts *linearly* on R by similarity transformations (see ref. [11] for details):

$$\text{If } g = g_1 \times g_2, \quad g(R) = g_1^{-1} g_2^{-1} \cdot R \cdot g_1 g_2. \tag{3}$$

3. Γ -orbits

The pictorial analysis already proposed in refs. [6,9] produces fig. 1 as a typical picture of the orbits of Γ (projection of the orbit on a coordinate two-plane).

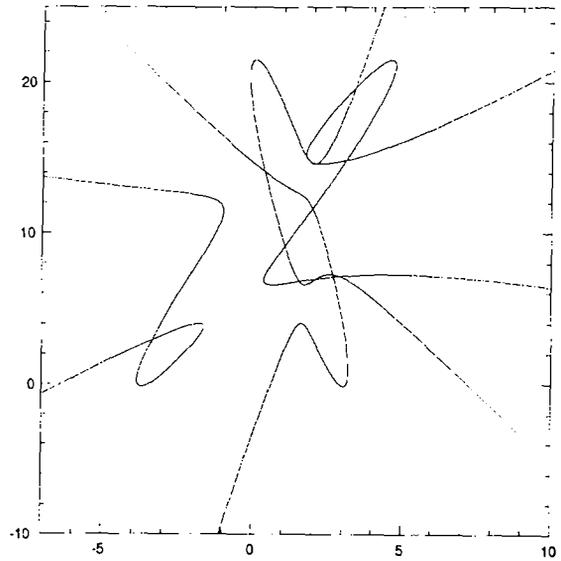


Fig. 1. Orbit of Γ .

The picture demonstrates the existence of *curves* on which the discrete orbit is dense. We have found 18 algebraically related quadratic polynomials (p_1, \dots, p_{18}) having simple transformations under Γ . Setting

$$\begin{aligned} l_1 &= a_1 a_4 - a_2 a_3, & l_2 &= d_1 d_4 - d_2 d_3, \\ l_3 &= b_1 b_4 - b_2 b_3, & l_4 &= c_1 c_4 - c_2 c_3, \\ l_5 &= a_1 d_1 - b_1 c_1, & l_6 &= a_2 d_2 - b_2 c_2, \\ l_7 &= a_3 d_3 - b_3 c_3, & l_8 &= a_4 d_4 - b_4 c_4, \\ l_9 &= a_1 d_4 - b_2 c_3 + a_4 d_1 - b_3 c_2, \\ l_{10} &= a_1 b_4 - b_2 a_3 + a_4 b_1 - b_3 a_2, \\ l_{11} &= c_1 d_4 - d_2 c_3 + c_4 d_1 - d_3 c_2, \\ l_{12} &= a_1 c_4 - a_2 c_3 + a_4 c_1 - a_3 c_2, \\ l_{13} &= b_1 d_4 - b_2 d_3 + b_4 d_1 - b_3 d_2, \\ l_{14} &= a_1 d_2 - b_2 c_1 + a_2 d_1 - b_1 c_2, \\ l_{15} &= a_1 d_3 - b_1 c_3 + a_3 d_1 - b_3 c_1, \\ l_{16} &= a_3 d_4 - b_4 c_3 + a_4 d_3 - b_3 c_4, \\ l_{17} &= a_2 d_4 - b_2 c_4 + a_4 d_2 - b_4 c_2, \\ l_{18} &= b_4 c_1 + c_4 b_1 - a_2 d_3 - a_3 d_2, \end{aligned}$$

and

$$\begin{aligned}
 p_1 &= l_1 + l_2, & p_2 &= l_1 - l_2, & p_3 &= l_3 + l_4, \\
 p_4 &= l_3 - l_4, & p_5 &= l_5 + l_8, & p_6 &= l_5 - l_8, \\
 p_7 &= l_6 + l_7, & p_8 &= l_6 - l_7, & p_9 &= l_9, & p_{18} &= l_{18}, \\
 p_{10} &= l_{10} + l_{11} + l_{12} + l_{13}, & p_{11} &= l_{10} + l_{11} - l_{12} - l_{13}, \\
 p_{12} &= l_{10} - l_{11} + l_{12} - l_{13}, & p_{13} &= l_{10} - l_{11} - l_{12} + l_{13}, \\
 p_{14} &= l_{14} + l_{15} + l_{16} + l_{17}, & p_{15} &= l_{14} + l_{15} - l_{16} - l_{17}, \\
 p_{16} &= l_{14} - l_{15} + l_{16} - l_{17}, & p_{17} &= l_{14} - l_{15} - l_{16} + l_{17},
 \end{aligned}$$

then

$$I(p_i) = \lambda \cdot \epsilon_i \cdot p_i, \tag{4}$$

$$t_1(p_i) = \pm p_i, \quad t_2(p_i) = \pm p_i. \tag{5}$$

Appropriate ratios of the p_i 's yield 17 algebraically related invariants of Γ . The equations of the curves of fig. 1 are obtained by setting these invariants to constants. They generically have the infinite group Γ as group of automorphisms, and are consequently of genus 0 or 1. The p_i 's verify three algebraic identities which may be written as equalities between polynomial expressions $\mathcal{H}_2, \mathcal{H}_3, \mathcal{H}_4$ written indifferently in respectively $\mathcal{P}_1 = \{p_1, p_2, p_3, p_4, p_{10}, p_{11}, p_{12}, p_{13}, p_9 + p_{18}\}$ and $\mathcal{P}_2 = \{p_5, p_6, p_7, p_8, p_{14}, p_{16}, p_{15}, p_{17}, p_9 - p_{18}\}$:

$$\mathcal{H}_i(\mathcal{P}_1) = \mathcal{H}_i(\mathcal{P}_2), \quad i=2, 3, 4, \tag{6}$$

with

$$\begin{aligned}
 \mathcal{H}_2(\mathcal{P}_1) &= 4(-p_1^2 + p_2^2 - p_3^2 + p_4^2) \\
 &\quad + p_{10}^2 + p_{11}^2 - p_{12}^2 - p_{13}^2 - 4(p_9 + p_{18})^2,
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{H}_3(\mathcal{P}_1) &= \frac{1}{2}(p_1 - p_3)(p_{10}^2 - p_{11}^2) \\
 &\quad + \frac{1}{2}(p_1 + p_3)(p_{12}^2 - p_{13}^2) \\
 &\quad + p_{13}p_{11}p_2 - p_{12}p_{11}p_4 + p_{13}p_{10}p_4 - p_{12}p_{10}p_2 \\
 &\quad + 2(p_9 + p_{18})(p_2^2 + p_3^2 - p_1^2 - p_4^2),
 \end{aligned}$$

$$\mathcal{H}_4 = \text{order four polynomial.}$$

There are 18 more quadratic polynomials q_1, \dots, q_{18} with transformation properties like (4), but not invariant by t_1 or t_2 . These polynomials can be obtained from the p_i 's by exchanging the two middle columns of R .

4. G-orbits

The action of G and Γ do not commute. However G and I do commute and t_1 (respectively t_2) sends orbits of G onto orbits of G . Consequently the action of Γ projects down to the quotient space $\mathcal{Q} = \mathcal{M}/G$. One should keep in mind that this quotient space may not be a smooth manifold, but rather a stratified space since all gauge orbits do not have the same dimension.

We use the previous results to construct a number of G -invariants. Indeed G acts linearly on p_1, \dots, p_{18} , (respectively q_1, \dots, q_{18}). Among the G - and Γ -invariants of the representation on the p_i 's, we get

$$\begin{aligned}
 \mathcal{I}_1 &= 2p_1 + p_9 + p_{18}, & \mathcal{I}_2 &= 2p_5 + p_9 - p_{18}, \\
 \mathcal{I}_3 &= 4p_2^2 + p_{10}^2 - p_{13}^2, & \mathcal{I}_4 &= 4p_6^2 + p_{14}^2 - p_{17}^2, \\
 \mathcal{I}_5 &= 24t_1^2 + 8t_3^+ t_3^- - 2t_5^+ t_5^-, & \\
 \mathcal{I}_6 &= 24t_2^2 + 8t_4^+ t_4^- + 2t_6^+ t_6^-, & \\
 \mathcal{I}_7 &= t_3^+ (t_5^-)^2 + t_3^- (t_5^+)^2 \\
 &\quad + 16t_1^3 - 16t_1 t_3^+ t_3^- - 2t_1 t_5^+ t_5^-, \\
 \mathcal{I}_8 &= t_4^+ (t_6^-)^2 + t_4^- (t_6^+)^2 \\
 &\quad + 16t_2^3 - 16t_2 t_4^+ t_4^- + 2t_2 t_6^+ t_6^-,
 \end{aligned}$$

with

$$\begin{aligned}
 t_1 &= \frac{1}{3}(p_1 - p_9 - p_{18}), & t_2 &= \frac{1}{3}(p_5 - p_9 + p_{18}), \\
 t_3^\pm &= p_3 \pm p_4, & t_4^\pm &= p_7 \pm p_8, \\
 t_5^\pm &= p_{11} \pm p_{12}, & t_6^\pm &= p_{15} \pm p_{16}.
 \end{aligned}$$

The G -invariants \mathcal{I}_i ($i=1, \dots, 8$) form a system of rank 7, and appropriate ratios yield six G - and Γ -invariants.

Similarly the simplest G - and I -invariants we get from the q_i 's are

$$\begin{aligned}
 \mathcal{J}_1 &= 4(q_1^2 - q_4^2 + q_5^2 - q_7^2) \\
 &\quad + 8q_9^2 - q_{11}^2 - q_{12}^2 + q_{14}^2 + q_{17}^2, \\
 \mathcal{J}_2 &= 4(q_2^2 - q_3^2 + q_6^2 - q_8^2) \\
 &\quad + 8q_{18}^2 - q_{10}^2 - q_{13}^2 + q_{15}^2 + q_{16}^2.
 \end{aligned}$$

We may complement them by any t_1 (and t_2) G -invariant of the form $\text{tr}(R^q)$, the simplest being the trace $\text{tr}(R)$. We thus get nine algebraically indepen-

dent gauge invariants, which define a finite covering over the quotient space Q .

5. Towards Bethe ansatz

One of the keys to the Bethe ansatz is the existence (see eqs. (B.10), (B11a) in ref [2]) of vectors which are pure tensor products (of the form $v \otimes w$) and which R maps onto the pure tensor product $v' \otimes w'$. If

$$v = \begin{pmatrix} 1 \\ p \end{pmatrix}, \quad w = \begin{pmatrix} 1 \\ q \end{pmatrix}, \quad v' = \begin{pmatrix} 1 \\ p' \end{pmatrix}, \quad w' = \begin{pmatrix} 1 \\ q' \end{pmatrix},$$

then the solution of the ‘‘pre-Bethe-ansatz’’ equation

$$R(v \otimes w) = \mu v' \otimes w' \tag{7}$$

verifies the two biquadratic relations

$$\begin{aligned} l_4 + l_{11}p - l_{12}p' + l_2p^2 + l_1p'^2 - (l_9 + l_{18})pp' \\ - l_{13}p^2p' + l_{10}pp'^2 + l_3p^2p'^2 \\ = 0, \end{aligned} \tag{8}$$

$$\begin{aligned} l_7 + l_{16}q - l_{15}q' + l_8q^2 + l_5q'^2 - (l_9 - l_{18})qq' \\ - l_{17}q^2q' + l_{14}qq'^2 + l_6q^2q'^2 \\ = 0. \end{aligned} \tag{9}$$

The group $G_{\text{Bethe}} \simeq \text{sl}_2 \times \text{sl}_2 \times \text{sl}_2 \times \text{sl}_2$ acts naturally on (7): the four copies of sl_2 act respectively on v, w, v', w' . This induces a linear action on R ,

$$R \rightarrow g_{11}^{-1} \cdot g_{21}^{-1} \cdot R \cdot g_{1R} \cdot g_{2R},$$

i.e. homographic transformations on p, p', q, q' , and linear transformations on the l_i 's. This linear representation has three invariants associated to each of its two nine-dimensional irreducible components. The two components reflect the partition of the l_i 's from (8), (9). The three invariants are nothing but $\mathcal{K}_2, \mathcal{K}_3, \mathcal{K}_4$. Furthermore \mathcal{K}_3 is invariant under the large group $\text{sl}_3 \times \text{sl}_3$, since it is the determinant of a 3×3 matrix the entries of which are the coefficients in (8).

The parametrization of (8), (9) is obtained as follows: the discriminant Δ of (8), considered as a degree two polynomial in p , is a polynomial of the form

$$\Delta = \alpha p^4 + 4\beta p^3 + 6\gamma p^2 + 4\beta' p + \alpha'. \tag{10}$$

The transformations of Δ under homographic trans-

formations of p' have two fundamental invariants g_2 and g_3 and the classical [13] modular invariant $J = g_3^2 / (g_2^3 - 27g_3^2)$.

$$g_2 = \alpha\alpha' - 4\beta\beta' + 3\gamma^2, \tag{11}$$

$$g_3 = \alpha\gamma\alpha' + 2\beta\gamma\beta' - \alpha\beta'^2 - \alpha'\beta^2 - \gamma^3; \tag{12}$$

g_2 and g_3 are also invariant under the homographic transformations of p (since Δ is).

Exchanging the role of p and p' , or, more remarkably, applying the same approach to eq. (9) leads to identical g_2 and g_3 . The latter is a direct consequence of the constraints (6), since g_2 and g_3 are expressible in terms of $\mathcal{K}_2, \mathcal{K}_3, \mathcal{K}_4$:

$$g_2 = \frac{4}{3}\mathcal{K}_4, \tag{13}$$

$$g_3 = \frac{1}{1728}(4\mathcal{K}_2^3 - 192\mathcal{K}_2\mathcal{K}_4 - 27\mathcal{K}_3^2). \tag{14}$$

For $J = \infty$ the elliptic parametrization degenerates into a rational one. This leads to a special variety in the parameter space and yields candidates for algebraic criticality and disorder conditions [1].

There exist a number of models for which $g_2^3 - 27g_3^2$ factorizes and becomes handable. Such models are obtained by imposing relations between the entries of R . We may consider for instance the following generalizations of the Baxter model:

$$\begin{aligned} (a_1 = d_4, \quad a_2 = d_3, \quad a_3 = d_2, \quad a_4 = d_1, \\ b_1 = c_4, \quad b_2 = c_3, \quad b_3 = c_2, \quad b_4 = c_1), \end{aligned} \tag{15}$$

$$\begin{aligned} (a_2 = a_3 = b_1 = b_4 = c_1 = c_4 = d_2 = d_3, \\ a_1 = d_4, \quad a_4 = d_1, \quad c_2 = b_3, \quad b_2 = c_3). \end{aligned} \tag{16}$$

Condition $J = \infty$ factorizes into simple low degree components. In the instance of (16), these components are of the typical form

$$\begin{aligned} (a_1 + b_3 - a_4 - b_2), \\ (a_1 + b_3 + a_4 + b_2 + 4a_2), \\ (a_1a_4 + b_2a_4 + b_3a_4 - a_4^2 - 2a_2^2), \end{aligned}$$

where one recognizes straightforward generalizations of the disorder and criticality conditions of the Baxter model [1]. Noticeably, these conditions appear on the same level.

The explicit elliptic parametrization shows that $t_1 t_2 I$ as well as the exchange of p and p' (respectively

q and q') are realized as a shift of the spectral parameter (see for instance ref. [3]).

Remark. We can perform the same symmetry analysis in higher dimension, since all the symmetry groups we have used here have their generalizations to dimension 3, 4, ... [9]. For instance the results of section 5 reproduce themselves, mutatis mutandis, yielding to an intertwining of three or more curves by matrices R living on higher dimensional varieties.

6. Conclusion

We have proved the existence of a canonical parametrization of the Boltzmann weights of the sixteen-vertex model. This parametrization by elliptic curves yields a framework for the use of the so-called inversion trick [4] in the exact (and straightforward) calculation of the partition function [14].

In addition to this parametrization, the complete analysis of the symmetries of the model brings to the light a remarkable algebraic variety ($J = \infty$). This variety is stable by the *entire* group of symmetries and is a candidate for the criticality and disorder conditions.

We actually believe that getting at the modular invariant J is extracting the very substance of the invariance properties. The foliation of the parameter

space by the values of J then becomes a structuring feature for any result concerning the phase space of the model.

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